Object position detector.

Patent number:

DE69324067T

Publication date:

1999-07-15

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Classification:

- International:

G06K11/16

- european:

Application number: DE19936024067T 19930607 Priority number(s): US19920895934 19920608

Also published as:

EP0574213 (A1) EP0574213 (B1)

Abstract not available for DE69324067T Abstract of correspondent: EP0574213

A proximity sensor system includes a sensor matrix array having a characteristic capacitance between horizontal and vertical conductors connected to sensor pads. The capacitance changes as a function of the proximity of an object or objects to the sensor matrix. The change in capacitance of each node in both the X and Y directions of the matrix due to the approach of an object is converted to a set of voltages in the X and Y directions. These voltages are processed by analog circuitry to develop electrical signals representative of the centroid of the profile of the object, i.e., its position in the X and Y dimensions. The profile of position may also be integrated to provide Z-axis (pressure) information.

FIG. 1a

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